Performability and Survivability Evaluation of Designing Disaster Tolerant Cloud Computing Systems

Agenda

Motivation

Approach

Architecture

Perfomability

Sensitivity Analysis

Survivability Evaluation

GeoClouds Tool

Why adopt cloud computing?

MOTIVATION

Why adopt cloud computing?

Cloud computing

- infrastructure is available on demand.
- Adopted as a service.
- Minimizes the costs of IT infrastructures
- Service Level Agreement (SLA).
  - Penalties may be applied if the defined availability level is not satisfied

Motivation

Large cloud service providers adopts service level agreements (SLAs) to regulate the availability of the cloud service.

- Costs
- Availability
- Performance (response time)

Service provider needs to carry out availability analysis

Motivation

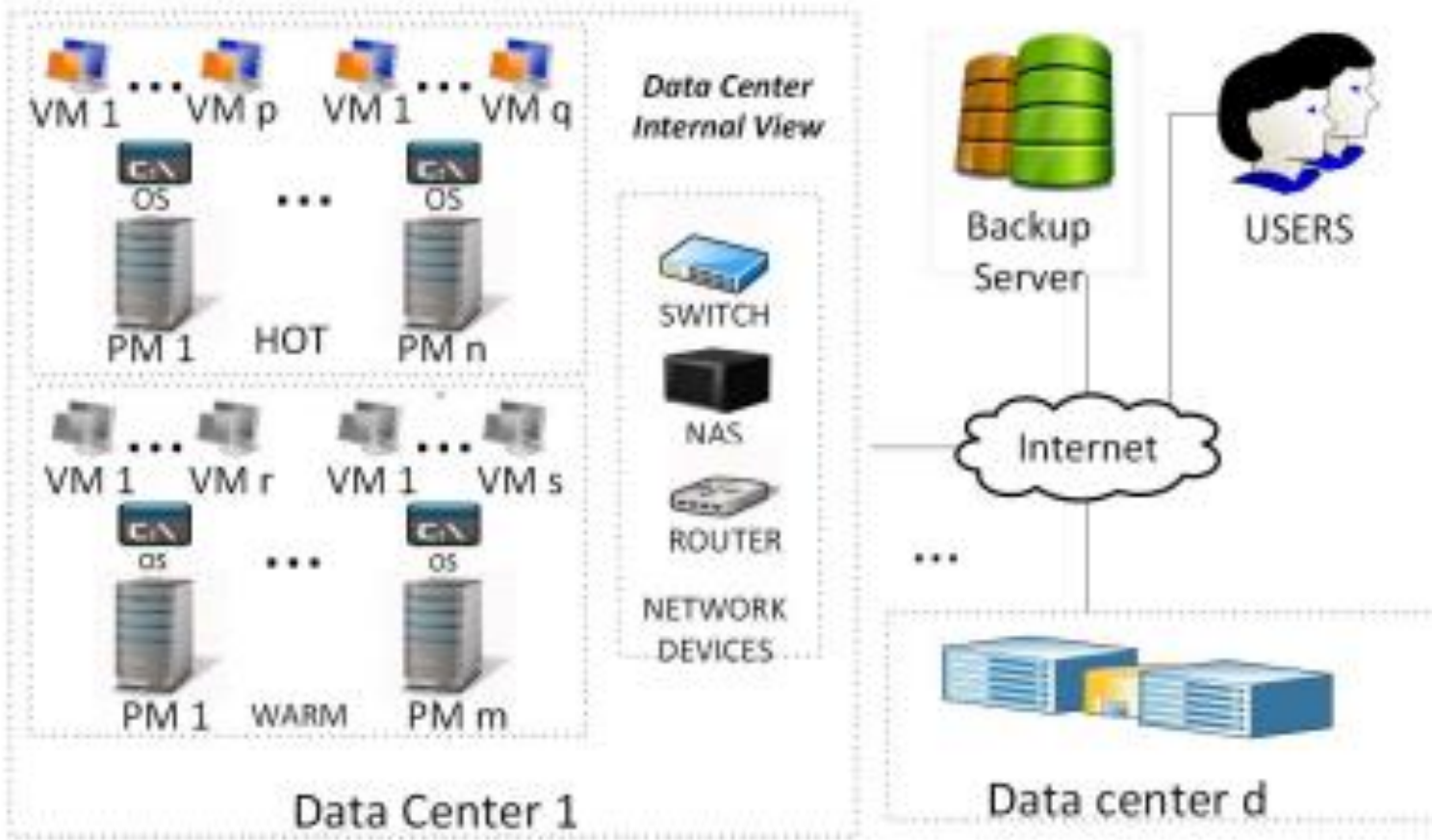
IaaS – computing resources in the form of virtual machines (VMs).

Disasters

- Multiple data located in different geographical locations
- Availability improvement
- VM migration time increases due to distance between data centers

ARCHITECTURE

Architecture



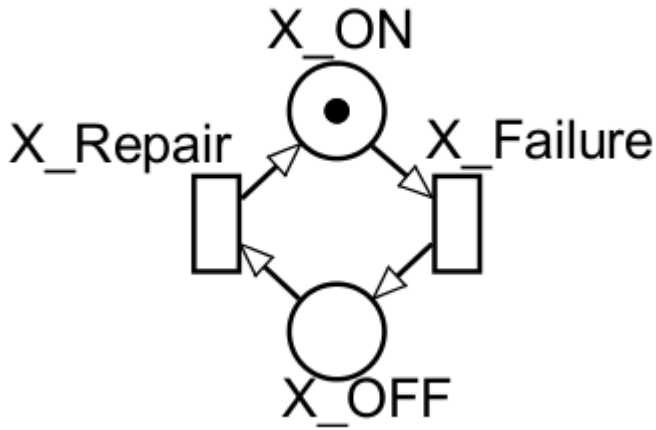
HIGH LEVEL MODEL

IaaS system corresponds to the tuple $G = (F_{lt}, T_{di}, T_{re}, MTT)$

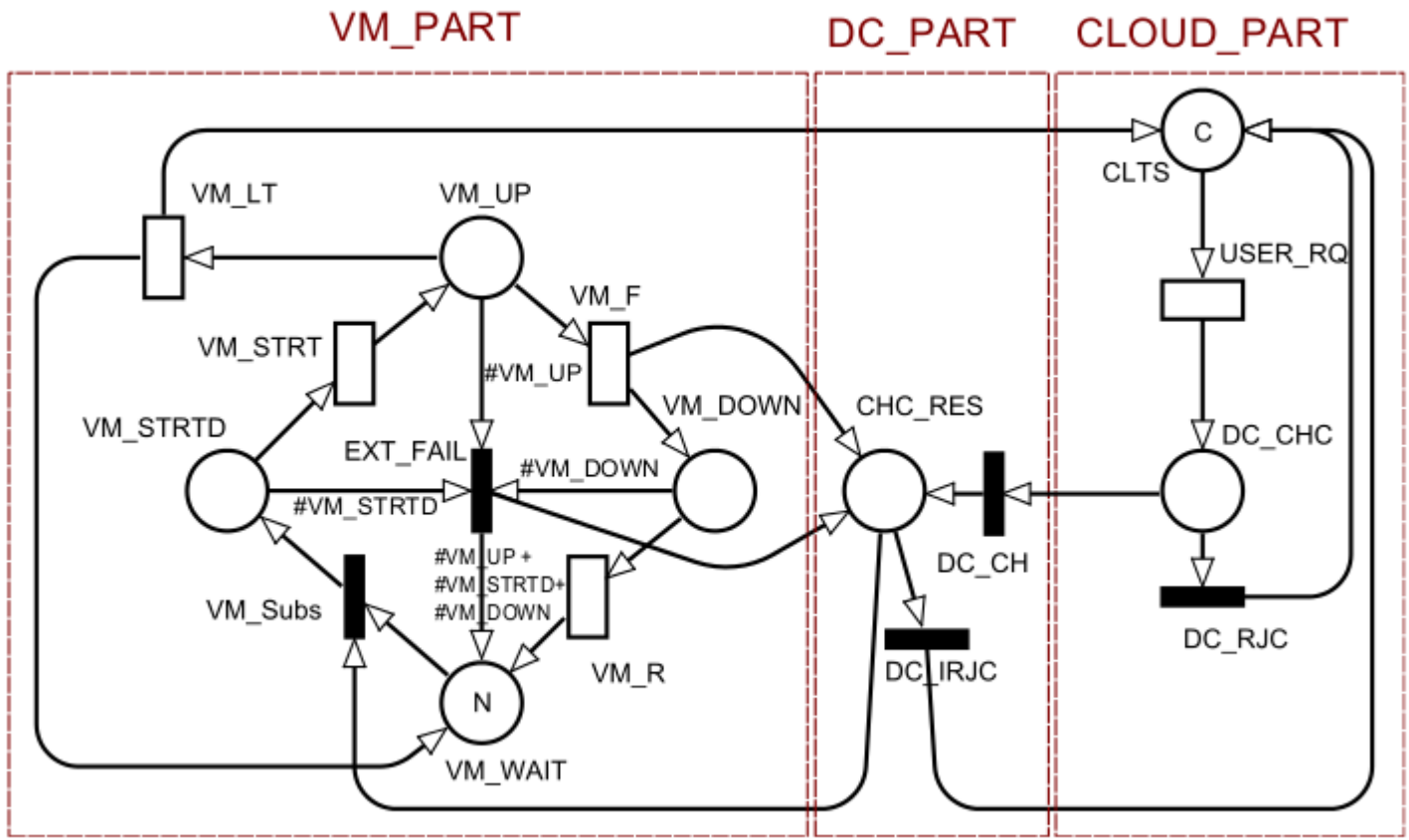
- F_{lt} is a finite set of facilities, including data centers and backup servers, such that $F_{lt} = D \cup BS$. D is a finite set of data centers and BS represents the set of backup servers;
- $T_{di} : F_{lt} \rightarrow f_{di}$ denotes the disaster occurrence function. For each facility $d_c \in F_{lt}$, a probability distribution function (PDF) f_{di} is associated. The function f_{di} provides the probability of a disaster for each instant t;
- $T_{re} : F_{lt} \rightarrow f_{re}$ represents the disaster recovery function. Similarly to the previous function, it associates a PDF (f_{re}) with each facility $d_c \in F_{lt}$. For each time t a probability of disaster recovery is provided;
- $MTT : F_{lt} \times F_{lt} \rightarrow f_{MTT}$ denotes the VM transmission function. The function relates a pair of facilities $(d_{c1}, d_{c2}) \in F_{lt} \times F_{lt}$ to a PDF f_{MTT}. The resulted function f_{MTT} provides the probability of finishing the data transmission between d_{c1} and d_{c2} at time t;

BUILDING BLOCKS

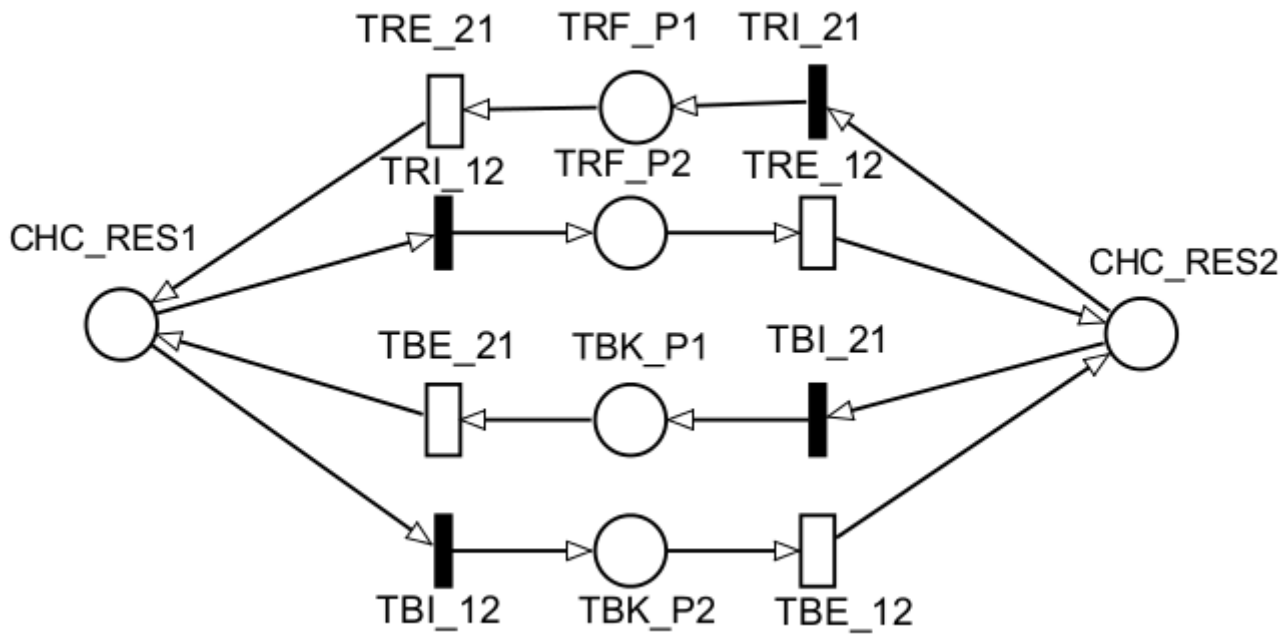
SIMPLE COMPONENT



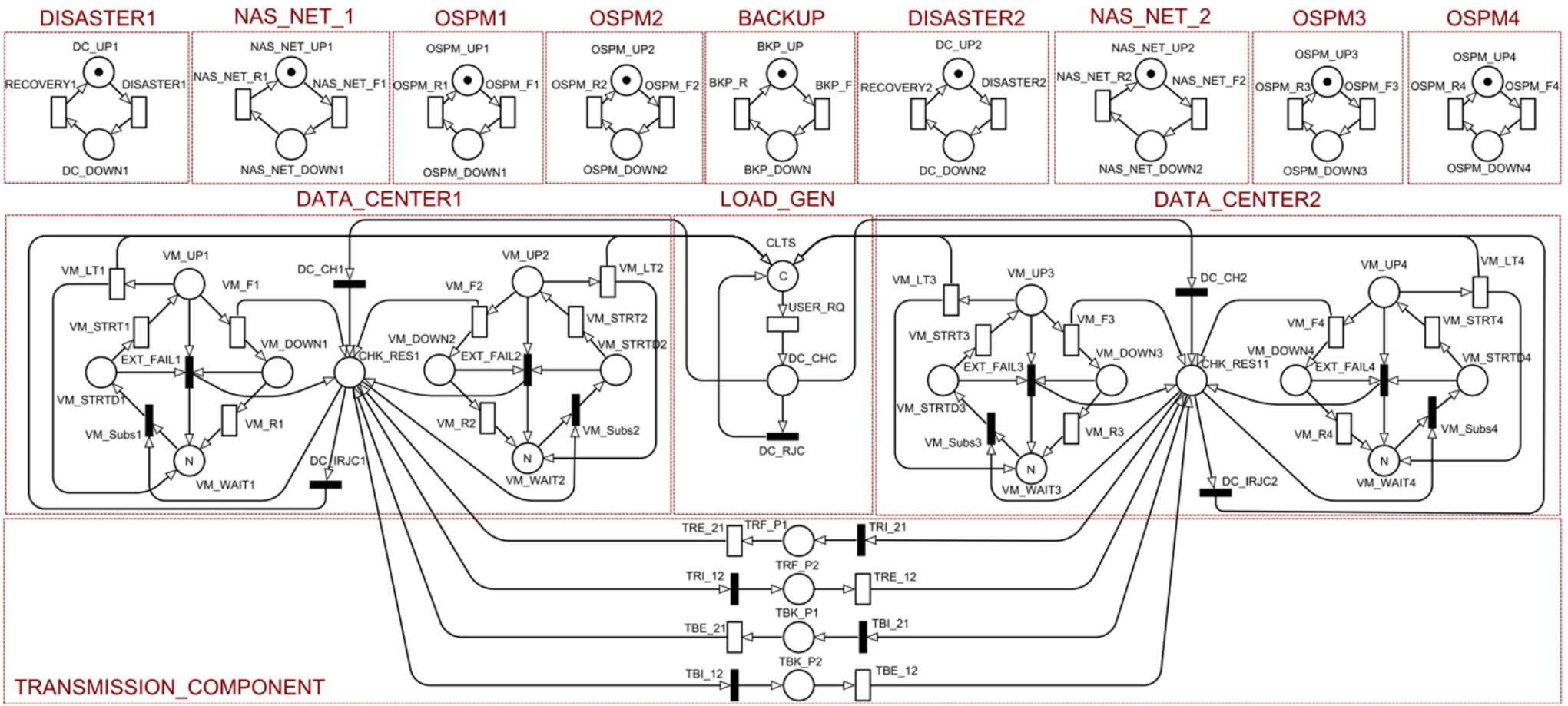
VM_BEHAVIOR


VM_PART
DC_PART
CLOUD_PART
C
CLTS
USER_RQ
DC_CHC
DC_RJC
VM_LT
VM_UP
VM_F
VM_STRT
#VM_UP
VM_DOWN
CHC_RES
VM_STRTD
EXT_FAIL
#VM_DOWN
#VM_STRTD
DC_CH
#VM_UP +
#VM_STRTD+
#VM_DOWN
VM_Subs
VM_R
DC_IRJC
N
VM_WAIT

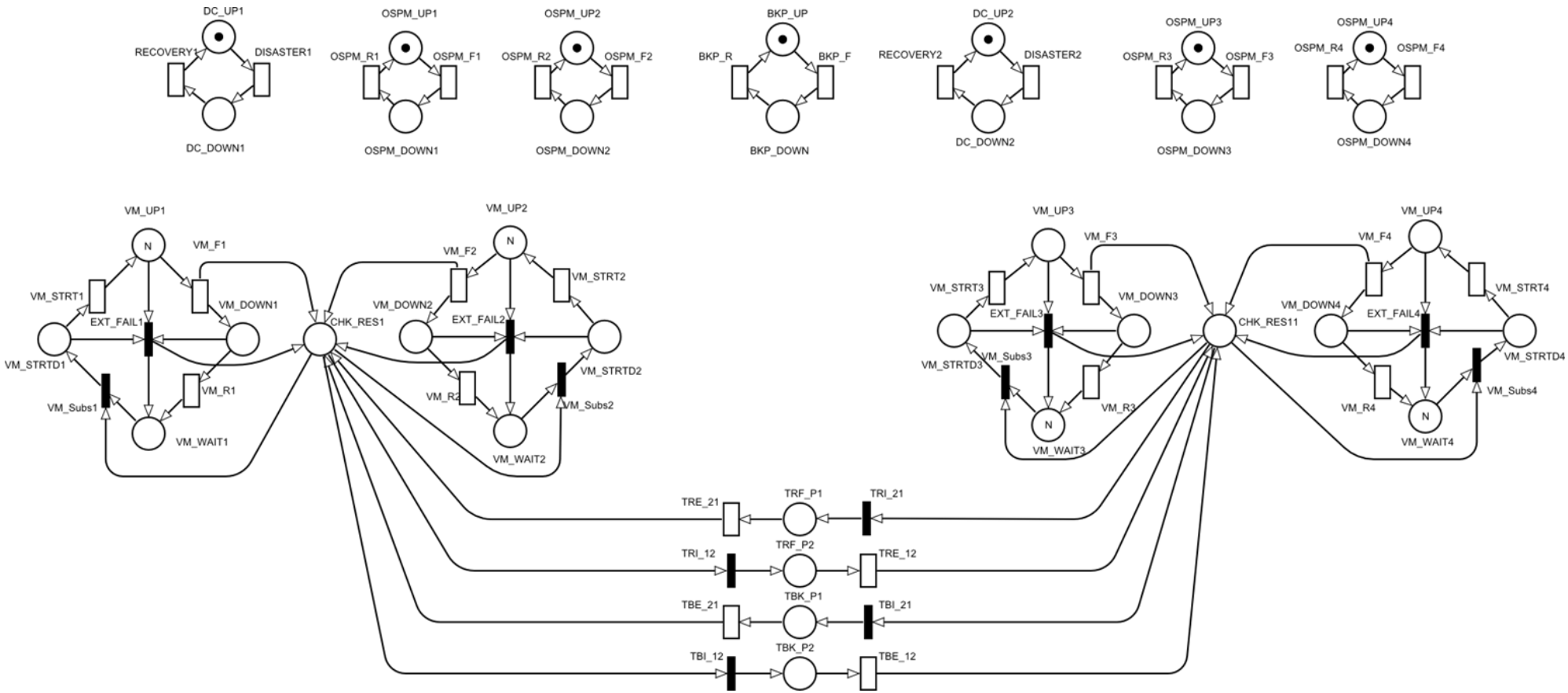
VM_TRANSMISSION



PERFORMABILITY MODEL



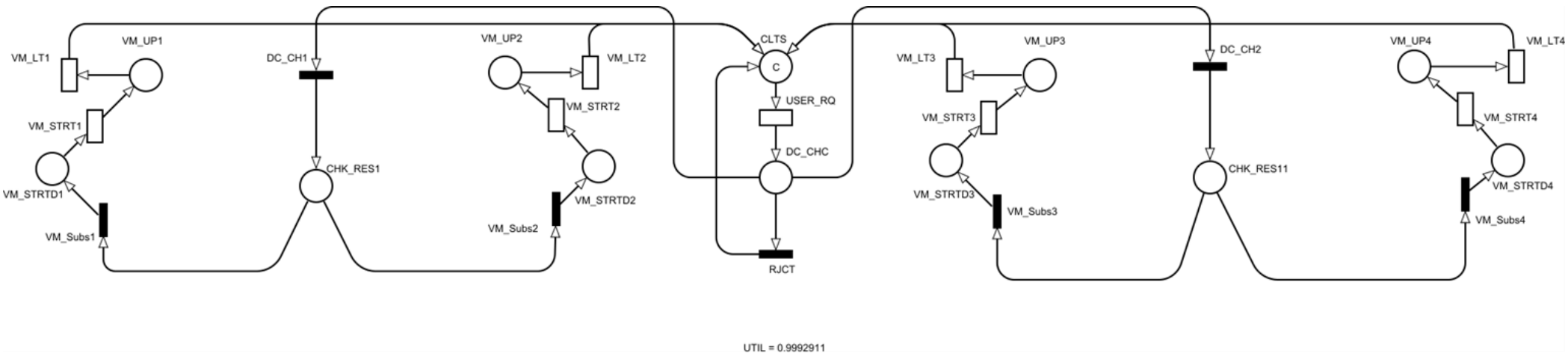
DEPENDABILITY MODEL



SPN GENERATION

```
01 SPN parseModel(G =< F_lt, T_di, T_re, MTT >)
02 {
03   SPN result = EMPTY_SPN;
04   bs = getBackupServer(F_lt);
05   result.increment(parseSimpleComponent(T_di(bs), T_re(bs)));
06   for each(d = < P_d, C_d > ∈ D){
07     result.increment(parseSimpleComponent(T_di(d), T_re(d)));
08     for each(pm = < V_p, S_p, os, hw, m > ∈ P_d){
09       result.increment(parseSimpleComponent(T_fr(os), T_rp(os)));
10       result.increment(parseSimpleComponent(T_fr(hw), T_rp(hw)));
11       result.increment(parseVmBehaviorComponent(V_p, S_p, m));
12     }
13     networkDependabilityParams := RBDEvaluation(C_d);
14     result.increment(parseSimpleComponent(networkDependabilityParams));
15   }
16   for each ((f1, f2) | f1, f2 ∈ F_lt and f1 ≠ f2){
17     result.increment(parseDataCenterTransmission(f1, f2, MTT));
18   }
19  return result;
```

PERFORMANCE MODEL



SPN GENERATION


```
01 SPN parsePerformanceModel(G =< F_lt, T_di, T_re, MTT, C_VM, T_req, L_t >)
02 {
03    SPN result = EMPTY_SPN;
04    for each(d = < P_d, C_d > ∈ D){
05       for each(pm = < V_p, S_p, os, hw, m > ∈ P_d){
06          result.increment(parseVmBehaviorComponent(V_p, S_p, m, C_VM, T_req,
L_t));
07       }
08    }
09   return result;
10 }
```

METRICS

* DEPENDABILITY MODELS

  AVAILABILITY = P{(#VMS_UP)>=REQ_VMS}

* PERFORMANCE

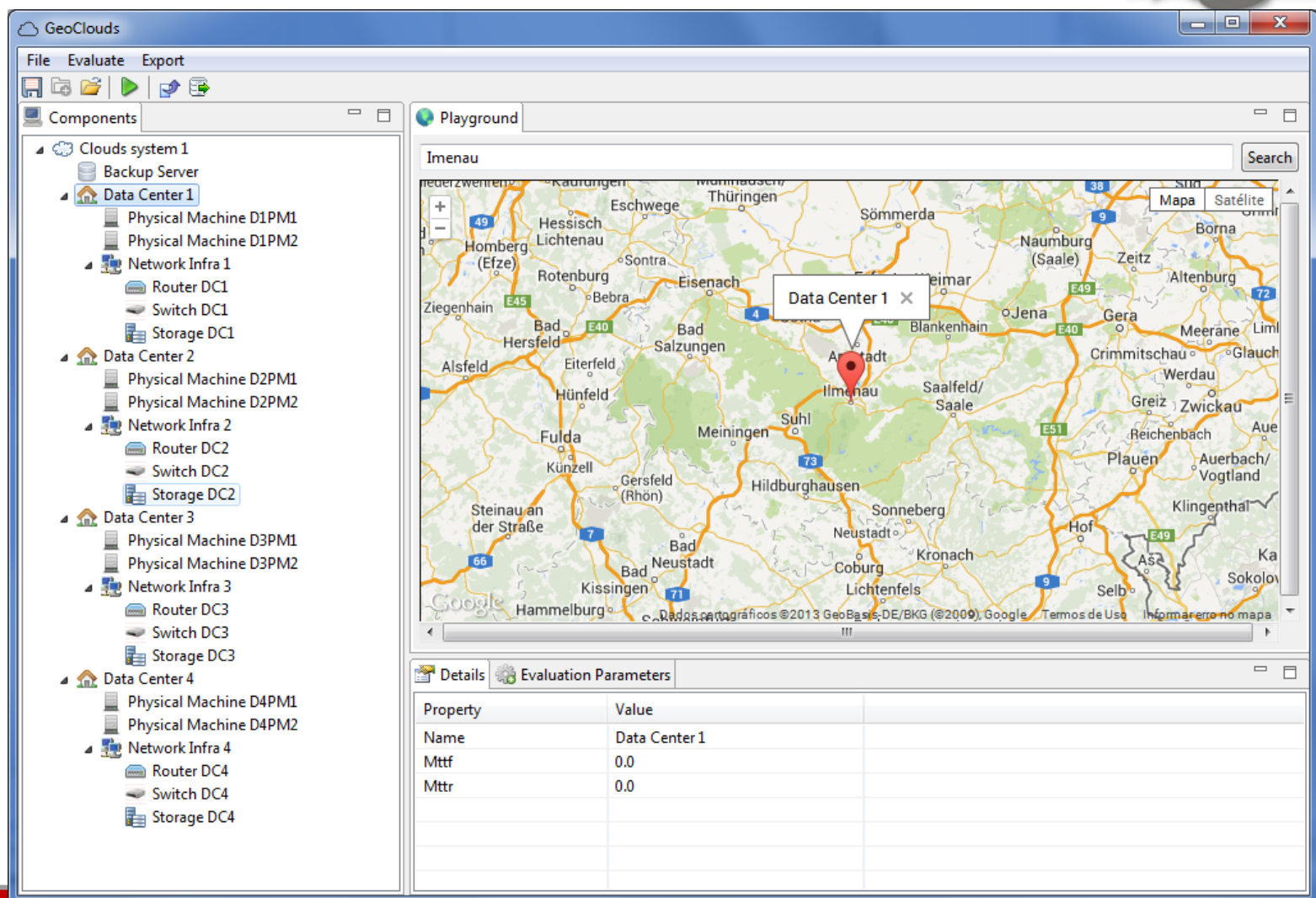
  UTILIZATION = E{#VMS_UP} / MAX_VMS

* PERFORMABILITY

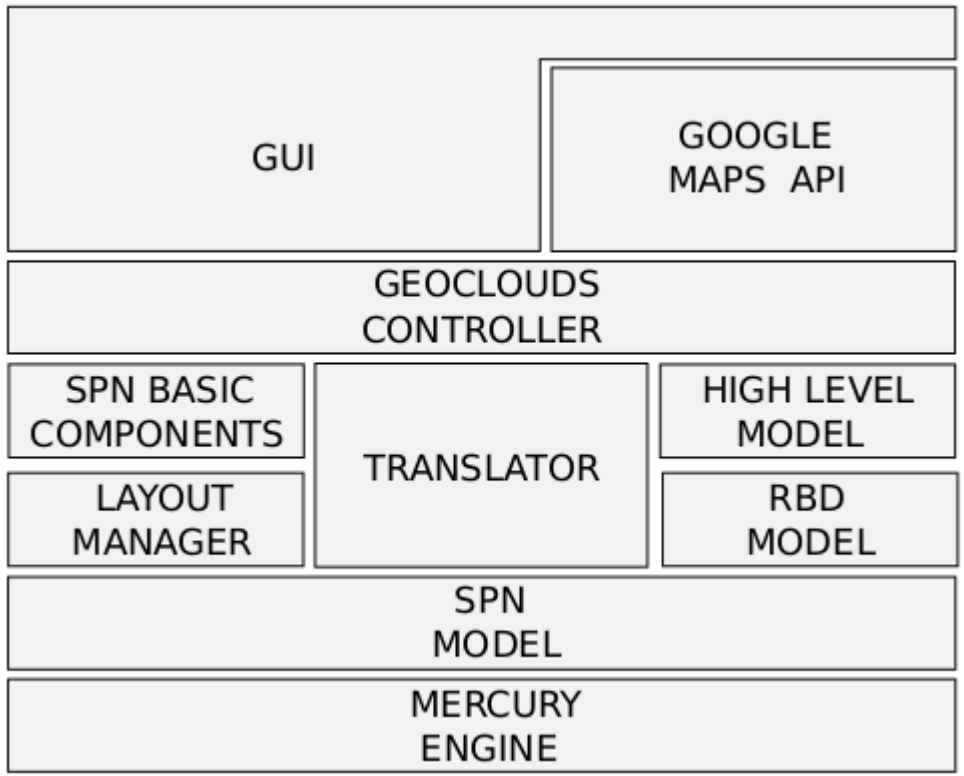
  UTILIZATION = E{#VMS_UP} / MAX_VMS

  UDOA= E{#VMS_UP} / E{#REQUESTED_VMS}

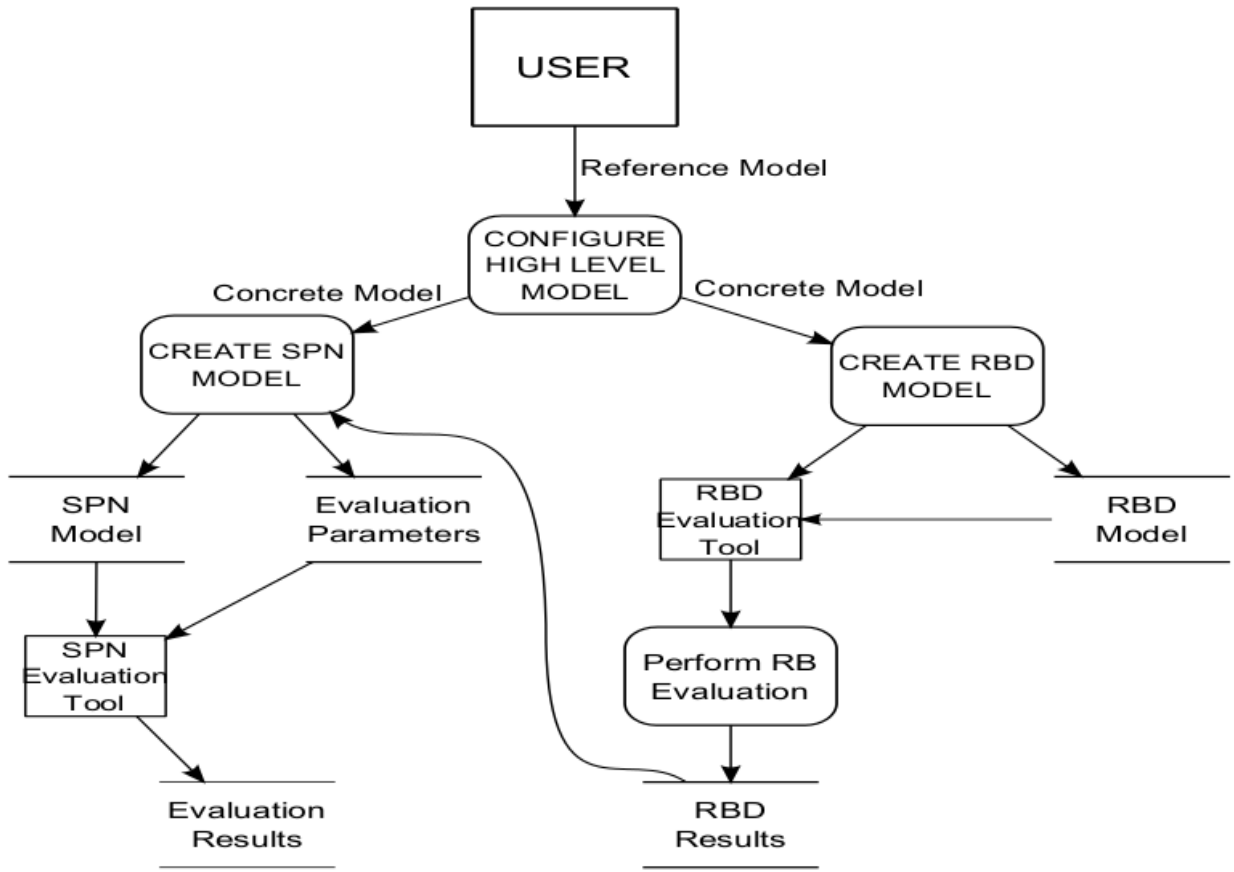
Geoclouds Modcs



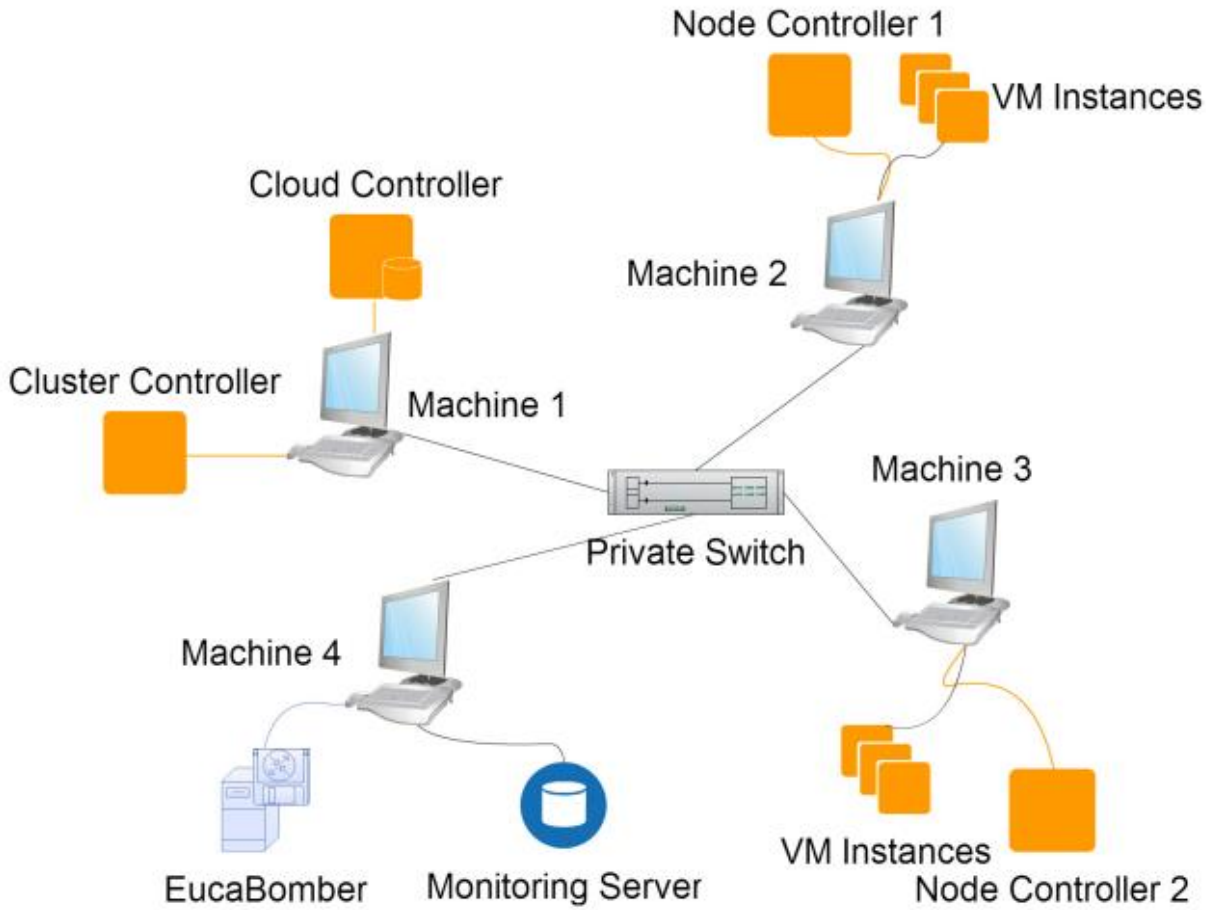
Geoclouds Modcs



Geoclouds Modcs



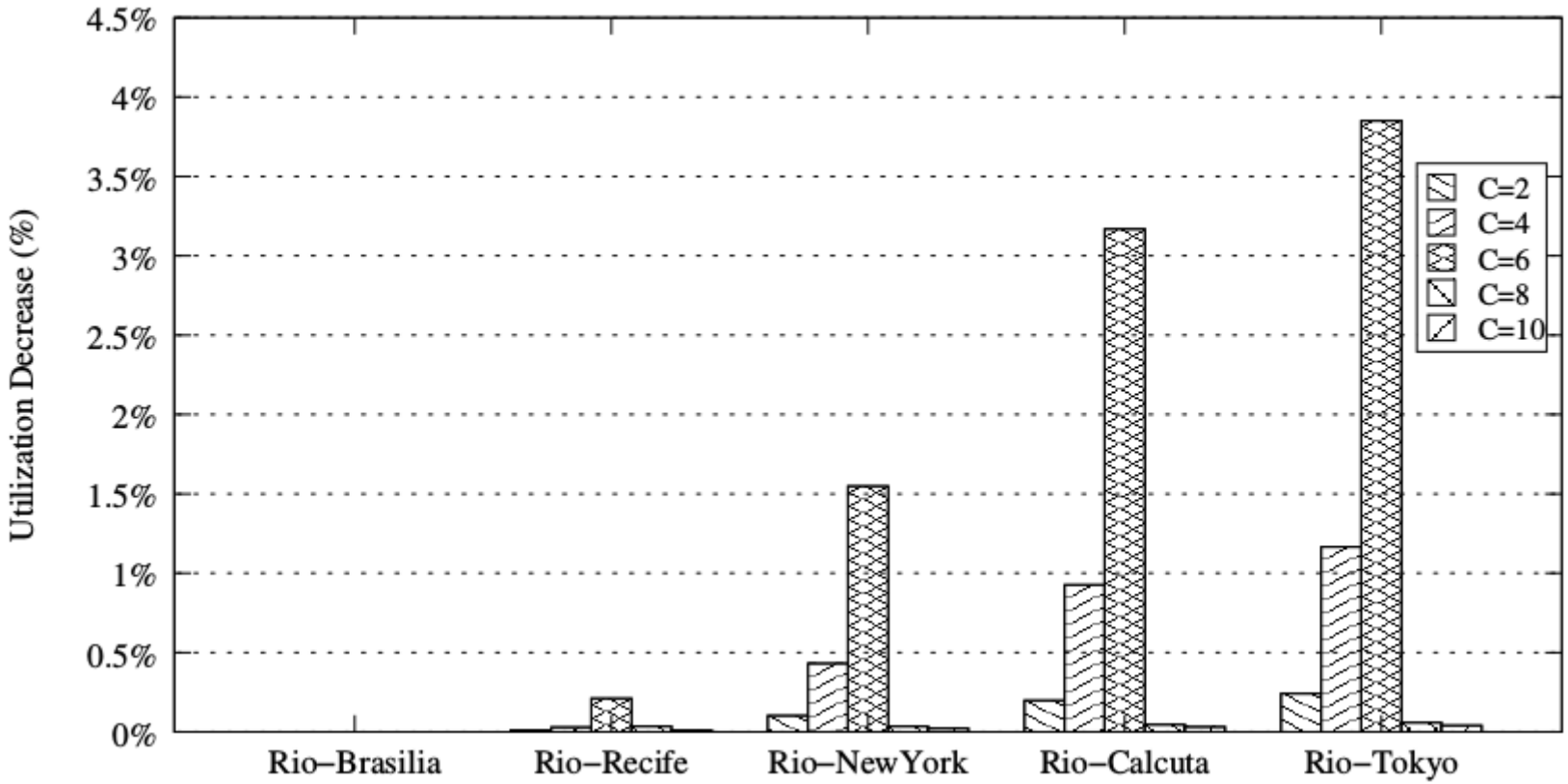
Validation


Node Controller 1
VM Instances
Cloud Controller
Machine 2
Cluster Controller
Machine 1
Machine 3
Private Switch
Machine 4
VM Instances
EucaBomber
Monitoring Server
Node Controller 2

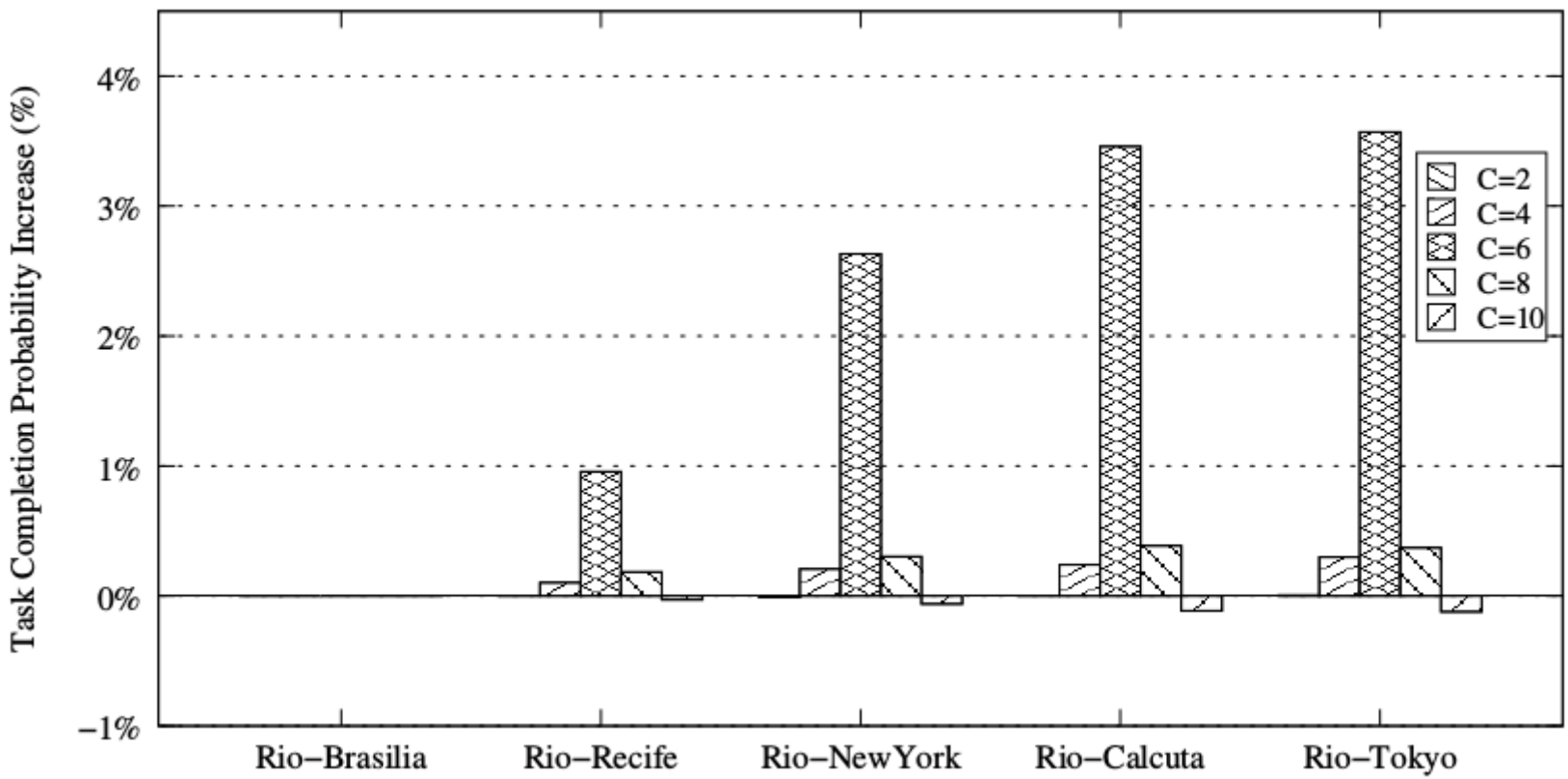
Validation

Scenario	N of Errors	Confidence interval of availability	Estimated value
A1	14	(0.993420433 , 0.998626244)	0.9935857
A2	20	(0.987658509 , 0.993537325)	0.9879326
B1	9	(0.807462045 , 0.965819035)	0.8279075
B2	20	(0.650996494 , 0.867691751)	0.7921259

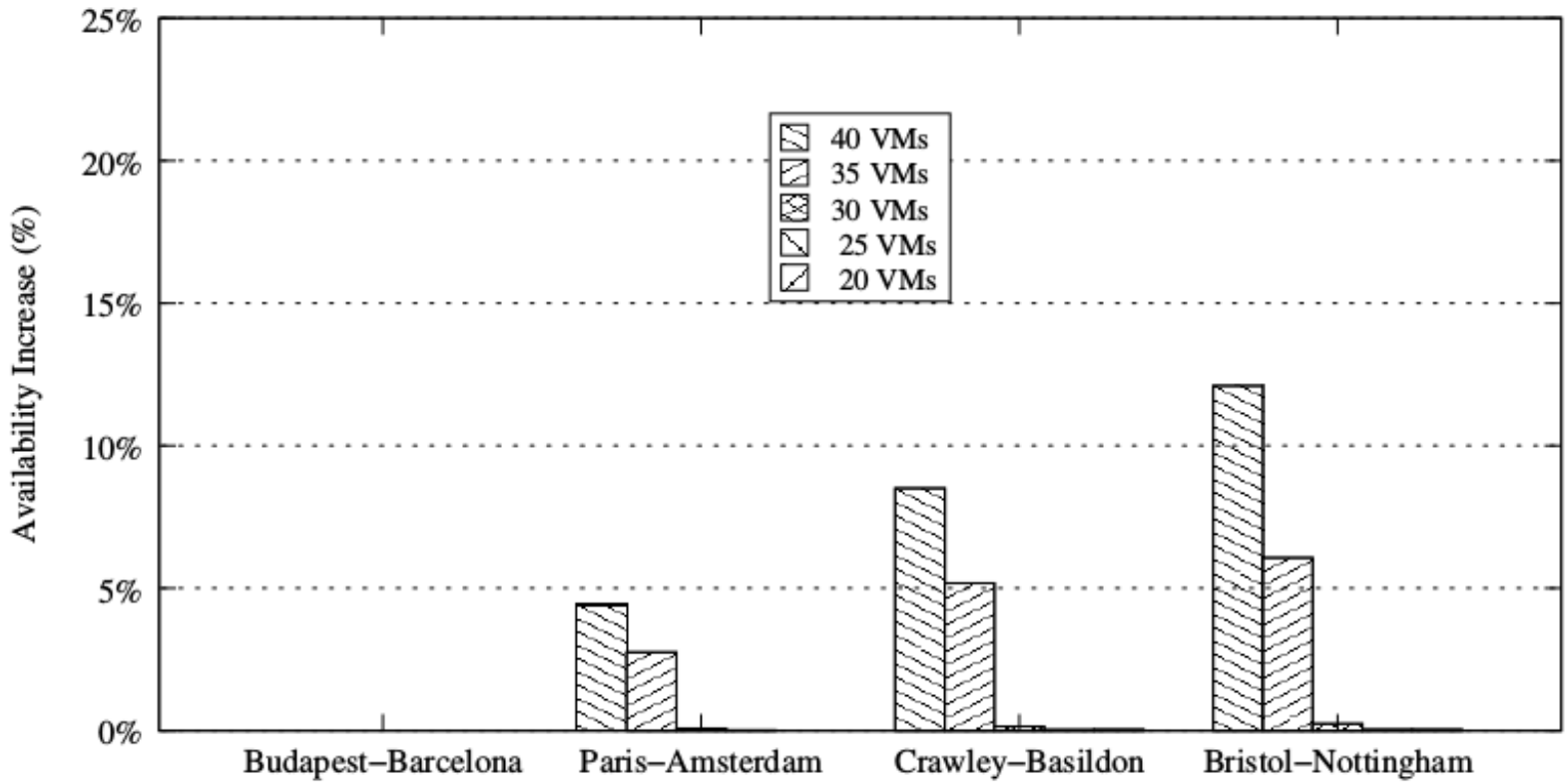
Case Study


4.5%
4%
3.5%
3%
2.5%
2%
1.5%
1%
0.5%
0%
Utilization Decrease (%)
C=2
C=4
C=6
C=8
C=10
Rio–Brasilia
Rio–Recife
Rio–NewYork
Rio–Calcuta
Rio–Tokyo

Case Study


Task Completion Probability Increase (%)
4%
3%
2%
1%
0%
−1%
Rio−Brasilia
Rio−Recife
Rio−NewYork
Rio−Calcuta
Rio−Tokyo
C=2
C=4
C=6
C=8
C=10

Case Study


25%
20%
15%
10%
5%
0%
Availability Increase (%)
40 VMs
35 VMs
30 VMs
25 VMs
20 VMs
Budapest–Barcelona
Paris–Amsterdam
Crawley–Basildon
Bristol–Nottingham

Conclusion

- Performability
- Survivability
- Tool
- Validation
- Sensitivity Analysis

Next Steps :

Keep Writing Papers ☺

Questions